# AVF 125S: Valve drive SUT with spring return

### How energy efficiency is improved

Electric cut-off and auto-adjustment to save energy.

### Areas of application

Actuation of through and three-way valves in the VXN/BXN, VUD/BUD and VUE/BUE, DN15 to DN50 series. For controllers with continuous output (0 - 10 V) or switching output (2-point or 3-point control).

### Features

- Actuator with spring return and pushing force of 500 N
- The return spring moves the actuator back to a pre-determined end position in the event of a power failure or the power being switched off or whenever a limiter is activated
- Two versions; NC closes the valve, NO opens the valve if the spring is activated
- Stepping motor with SUT (Sauter Universal Technology) electronic control unit and electronic load-dependent cut-off
- Automatic detection of control signal applied (continuous or switching)
- The type of characteristic curve (linear, quadratic or equal percentage) can be adjusted in the drive
- Direction of travel can be selected via screw terminals when making electrical connection or remotely
- Coding switch for selection of characteristic and running time (60 or 120 sec.)
- Maintenance-free gearbox and holding magnet
- LED display

## **Technical description**

- 24 V~ power supply
- Two-part housing made of self-extinguishing plastic, lower section black, cover transparent
- Body of gearbox and mounting bracket for fitting valve made of cast zinc
- Electrical connections (max. 1.5 mm<sup>2</sup>) with screw terminals
- Cable entry M20 × 1.5
- Installation position: vertical to horizontal, but not upside down

Туре	Runnin se	g time c	Reset func- tion	Pushing <sup>1)</sup> force	Power	Weight
	Motor	Spring		Ν		kg
For valves with equal-percentage characteristic, can be switched over to linear						
AVF 125S F132	60 / 120	$18\pm10$	closed (NC)	500	24 V~	2,4
AVF 125S F232	60 / 120	$18\pm10$	open (NO)	500	24 V~	2,4

Positioner: Control signal 1 Control signal 2 Position feedback signal		010V, R <sub>j</sub> = 100 kΩ 420 mA, R <sub>j</sub> = 50 Ω 010V, load > 2,5 kΩ		Starting point U <sub>0</sub> Control span ∆U Switching range X <sub>Sh</sub>	0 or 10 V 10 V 200 mV
Power supply 24	V~ <sup>2)</sup>	± 20%, 50(	60 Hz	Degree of protection <sup>3)</sup> Protection class	IP 54 (EN 60529) III as per IEC 60730
Power consumption					
AVF 12 . S F. 32		5 W	8,4 VA	Wiring diagram AVF 125	A10455
on starting		30 VA (max. 1s) 4)		Dimension drawing	M07429
Nominal stroke 5)					
AVF 125S		8,0 mm		Fitting instructions AVF 125	MV 506067
Max. media temperature		100 °C		Declaration on materials	MD 51.368
Permissible ambient temp.		-1055 °C			
Ambient humidity		< 95 %rh			
		without cond	lensation		

1) Max. pushing force: 550 N or, with spring return, 1500 N

2) 24V= not possible

Degree of protection IP 54 only with M20 cable screw fitting
On starting or after spring return operation

4) On starting or after spring return operation
5) Maximum stroke of drive = 10.0 mm









Accessories				
0313529 001*	Split-range unit for settings sequences. MV 505671; A09421			
0370880 001	Mechanical stroke indicator; MV 505517			
0370881 001*	Auxiliary change-over contacts <sup>1)</sup> , simple; MV 505517			
0370882 001*	Auxiliary change-over contacts <sup>1</sup> ), simple, and pot. 2000 $\Omega$ , 1 W; 24 V; MV 505517			
0370882 006*	Auxiliary change-over contacts <sup>1</sup> ), simple, and pot. 1000 $\Omega$ , 1 W; 24 V; MV 505517			
0370883 001*	Potentiometer 2000 Ω, 1 W; 24 V; MV 505517			
0370883 006*	' Potentiometer 1000 Ω, 1 W; 24 V; MV 505517			
0372249 001*	72249 001* Intermediate piece required for media temperature >100 °C for BXN / VXN			
	(recommended for temperature < 10 °C); MV 505932			
0372460 001	<b>)372460 001</b> Cable screw fitting (plastic M20×1,5) incl. locking nut and gasket, max. 2 pcs.			
*) Dimension drawing or wiring diagram are available under the same number				
1) Infinitely variable; max. load 2 (1) A, 12250 V~, min. load 250 mA, 12 V~				

#### Operation

On starting the unit for the first time (after applying power), or on re-starting the unit after the reset function has been triggered, there is a wait of 45 seconds for the reset function to become operable. Depending on how it is connected (see wiring diagram), the actuator can be used as a continuous drive (0...10V and/or 4...20 mA), a 2-point drive (open/close) or a 3-point drive (open/stop/close) with

drive (0...10V and/or 4...20 mA), a 2-point drive (open/close) or a 3-point drive (open/stop/close) with intermediate position. When control signals 1 (3u / 03) and 2 (3i / 04) are connected simultaneously, the input with the higher value has priority.

The running time can be matched to the requirements of the task using switches S1 and S2. The characteristic (equal-percentage, linear or quadratic) can be selected via switches S3 and S4. The AVF 124S is combined with valves that have a linear basic characteristic such as the VXN and BXN valves. The AVF 125S is combined with valves that have an equal-percentage basic characteristic such as the VUD, BUD, VUE and BUE valves. The AVF 125S can be fitted on a valve with a linear characteristic (e.g. VUE 050F200), but you must pay attention to the position of the coding switches.

#### Connected as a 2-point actuator

Opening/closing can be effected via two wires. Power is applied to the drive via terminals 1 / MM and 2a / 01. When power is connected to terminal 2b / 02, the valve's control passage opens. When power is switched off, the drive goes to the opposite end position and closes the valve.

#### Connected as a 3-point control unit

By connecting power to terminal 2a / 01 or 2b / 02, the valve can be moved to any position. The coupling rod extends and opens the valve if power is applied to terminals 1 / MM and 2b / 02. It retracts and closes the valve if the power circuit is closed via terminals 1 / MM and 2a / 01.

In the end positions (on hitting a stop in the valve or reaching the maximum stroke) or in the event of an overload, the electronic motor cut-off responds (no end switches). The direction of the stroke can be changed by swapping the power-supply wires over (2a, 2b / 01, 02).

#### Connections for control voltage 0...10V and/or 4...20 mA

The integrated positioner controls the drive as a function of the controller's positioning signal y.

The voltage signal of 0...10 V– is connected via terminal 3u / 03 and the current signal is connected via terminal 3i / 04.

Direction of operation 1 (mains power to internal connection 2a / 01):

the coupling rod extends and opens the valve (control passage) as the positioning signal rises. Direction of operation 2 (mains power to internal connection 2b / 02):

the coupling rod retracts and closes the valve (control passage) as the positioning signal rises. The starting point and the control span are both permanently set.

There is a split-range unit available (as an accessory) for setting partial ranges (only for control signal 1). After the emergency position has been implemented, or when there is a power failure, the drive readjusts itself automatically. If an adjustment is needed, it can be triggered via the pushbutton on the electronic circuit board (top left).

After power has been applied, the stepping motor moves to the lower stop, connects to the valve spindle and moves to the upper stop in the valve, thereby determining the closed position. Depending on the control voltage, any stroke between 0 and 8 mm can then be obtained. Thanks to the electronics unit, no steps can be lost, and the drive needs no periodical re-adjustment. Parallel operation of more than one drive of the same type is guaranteed.

If the power supply fails or is switched off, or a monitoring contact is triggered, the retention magnet releases the gears and the pre-tensioned spring moves the drive – depending on the variant – into the end position. In so doing, the drive's control function is blocked for 45 seconds so that the end position is always attained. The reset function is retarded depending on the speed, so that no pressure surges can occur in the line.

The feedback signal  $y_0 = 0...10V$  corresponds to the effective stroke of 0 to 8 mm. If the control signal (0...10V) is interrupted and direction of operation 1 is connected, the valve closes fully (0% position).

The valve's characteristic can be selected using the coding switch. The characteristics can be generated only if the drive is used as a continuous drive. Other switches enable the running times to be set. These can be applied irrespective of whether the 2-point, 3-point or the continuous function has been chosen.

## Coding switches for running time selection

AVF 124S, AVF 125S

Run time per mm	Switch coding	Run time for 8 mm stroke		
7,5 s	1 2 3 4 On Off	60 s ± 2		
	1 2 3 4 On Off			
15 s	1 2 3 4 On off On off	120 s ± 4		
factory setting				

## Coding switches for characteristics selection

AVF 125S



## LED indicator: normal operation AVF 125S



### LED indicator: safety function



#### Split-range unit (accessory 0313529)

The starting point  $U_0$  and the control span  $\Delta U$  can be set using the potentiometer. This makes it possible to activate several regulating units in sequence or in cascade using the controller's control signal. If this accessory is fitted, it is not possible to fit any auxiliary contacts or a potentiometer.

### **Engineering and fitting notes**

The ingress of condensate, drops of water etc. along the valve spindle and into the drive should be prevented.

The drive and valve are fitted together by hand, then the screws are tightened; no further adjustment is necessary. The drive is delivered ex works in the open or middle position.

On the 'normally closed' version, the spacer on the lifting rod has to be removed when the valve is fitted.

The idea of having a stepping motor and an electronics unit ensures that several actuators of the same type can be run in parallel.

The maximum number of accessories that can be fitted is one stroke indicator plus one additional accessory: auxiliary contacts, potentiometer or combination, or split-range unit.

The power consumption on starting is relatively high. It occurs only on a cold start or after the spring return has been activated and lasts max. 1s. A random delay of up to 20s is fitted in the drive so that, if several drives are run in parallel, they do not all cut in at the same time. Depending on the length of the cable, the cross-section of the cable or the transformer rating should be chosen accordingly:-

Length of cable	Cross-section of cable	Transformer rating
Max. 30 m	0,75 mm <sup>2</sup>	30 VA
Max. 60 m	1,5 mm <sup>2</sup>	30 VA
Max. 100 m	1,5 mm <sup>2</sup>	50 VA

**Fitting outdoors.** If the devices are fitted outdoors, we recommend that additional measures be taken to protect them against the effects of the weather.

#### Additional technical information

Transparent cover without lever for manual adjustment. The black housing holds the stepping motor and the electronic control unit. Underneath is the maintenance-free gear unit, the spring and the retention magnet. By breaking out a pre-scored circle in the housing, it is possible to create an aperture to fit a second M20 cable screw fitting.

Auxiliary change-over contacts

Switch rating: max. 230 V a.c.; min. current 20 mA at 20V Switch rating: 4...30 V d.c.; current 1...100 mA

#### **CE conformity**

EMC directive 2004/108/EC	Machine directive 98/37/EEC/I/E
EN 61000-6-1	EN 1050
EN 61000-6-2	
EN 61000-6-3	
EN 61000-6-4	

### Wiring diagram



#### Accessories

## 370881

370882





A01363



NC = normally closed NO = normally open

0313529 24V~ у 0...10 V 2 33 1 2a Зu MM 01/02 03 A/B AVM . . .S AVF S ASF S AXM S ASM S Uo ΔU A09421c

## **Dimension drawing**



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## **Sauter Components**



